

Measuring HMM similarity with the Bayes probability of error

An application to on-line handwritten character recognition

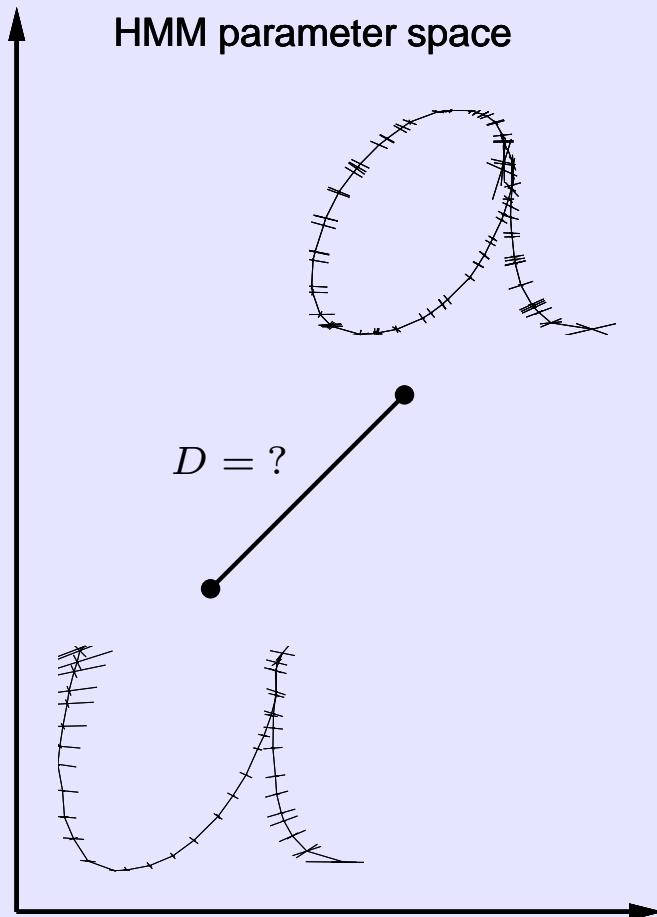
Dipl.-Inf. Claus Bahlmann

Abstract

- Introduction
- Sequence Classifiers
 - Dynamic Time Warping (DTW)
 - Statistical DTW/HMM
- Proposed HMM Similarity Measure
- Experiments with on-line handwritten characters

Introduction

Problem



Context

On-line handwritten character recognition

Why do we need HMM distance?

- detection of “close” competing HMMs
- interpretation of misclassifications
- monitoring iterative training process
- HMM clustering

Approach

classification-oriented

Dynamic Time Warping (DTW)

Alignment distance:

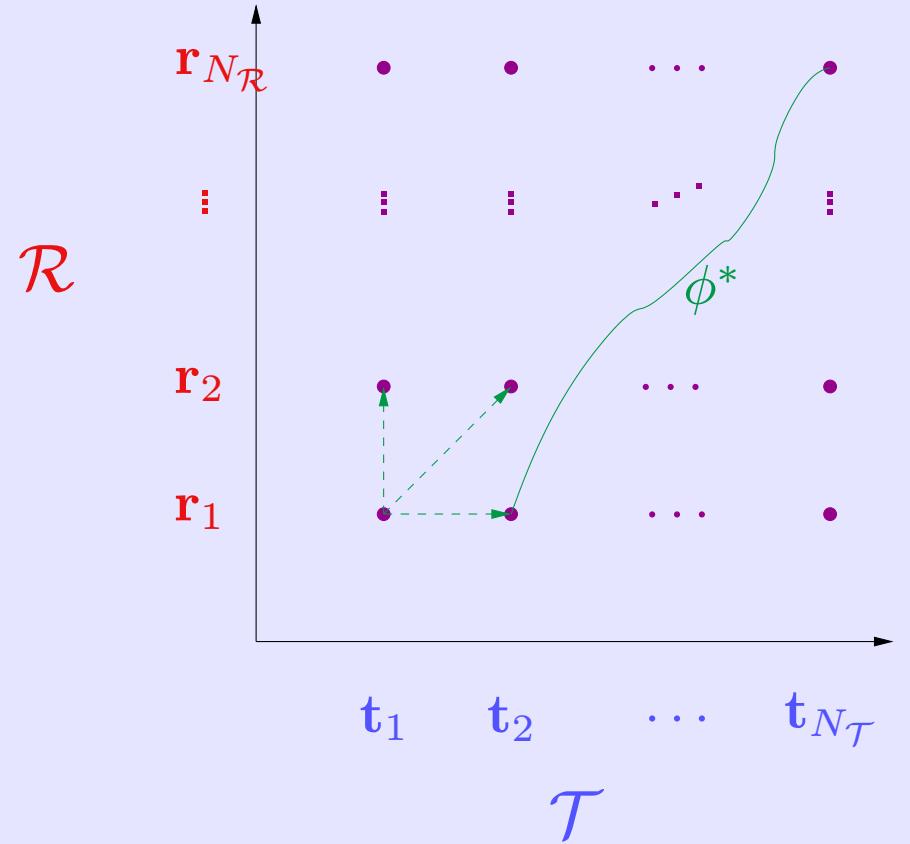
$$D_{\phi}(\mathcal{T}, \mathcal{R}) = \frac{1}{N} \sum_{i=1}^N d(\mathbf{t}_{\phi_{\mathcal{T}(i)}}, \mathbf{r}_{\phi_{\mathcal{R}(i)}})$$

Viterbi distance:

$$D(\mathcal{T}, \mathcal{R}) = D_{\phi^*}(\mathcal{T}, \mathcal{R}) = \min_{\phi} \{D_{\phi}(\mathcal{T}, \mathcal{R})\}$$

Local distance: Euclidean distance

$$d(\mathbf{t}_i, \mathbf{r}_j) = \|\mathbf{t}_i - \mathbf{r}_j\|$$



Statistical DTW (SDTW), HMM

Alignment distance:

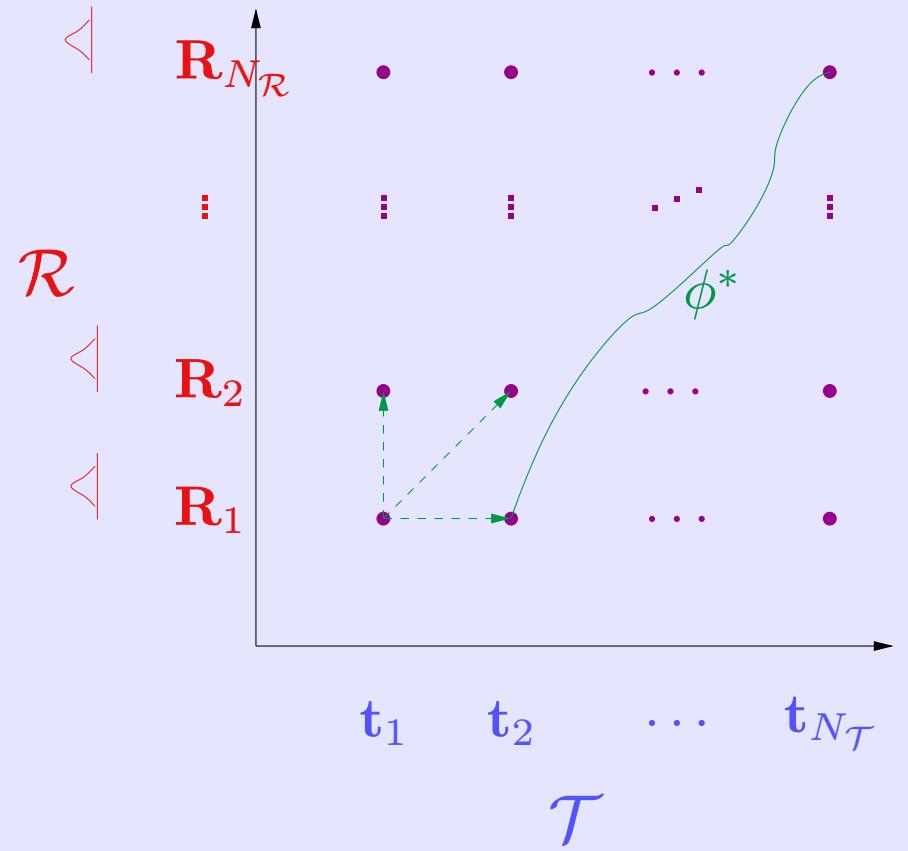
$$D_{\phi}(\mathcal{T}, \mathcal{R}) = \frac{1}{N} \sum_{i=1}^N d(\mathbf{t}_{\phi \mathcal{T}(i)}, \mathbf{R}_{\phi \mathcal{R}(i)})$$

Viterbi distance:

$$D(\mathcal{T}, \mathcal{R}) = D_{\phi^*}(\mathcal{T}, \mathcal{R}) = \min_{\phi} \{D_{\phi}(\mathcal{T}, \mathcal{R})\}$$

Local distance: $-\log$ a-posteriori probability

$$d(\mathbf{t}_i, \mathbf{R}_j) = -\log P(\mathbf{t}_i | \mathbf{R}_j)$$



SDTW/HMM Similarities

Alignment distance:

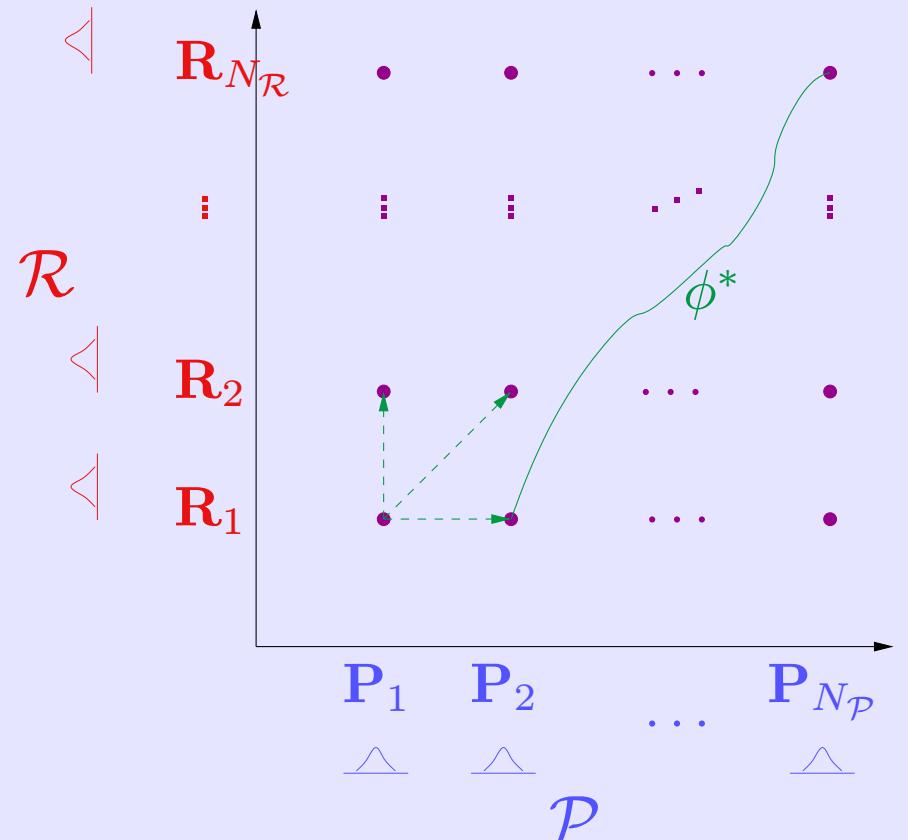
$$D_{\phi}(\mathcal{P}, \mathcal{R}) = \frac{1}{N} \sum_{i=1}^N d\left(\mathbf{P}_{\phi_{\mathcal{T}(i)}}, \mathbf{R}_{\phi_{\mathcal{R}(i)}}\right)$$

Viterbi distance:

$$D(\mathcal{P}, \mathcal{R}) = D_{\phi^*}(\mathcal{P}, \mathcal{R}) = \min_{\phi} \{D_{\phi}(\mathcal{P}, \mathcal{R})\}$$

Local distance:

$$d(\mathbf{P}_i, \mathbf{R}_j) = ?$$

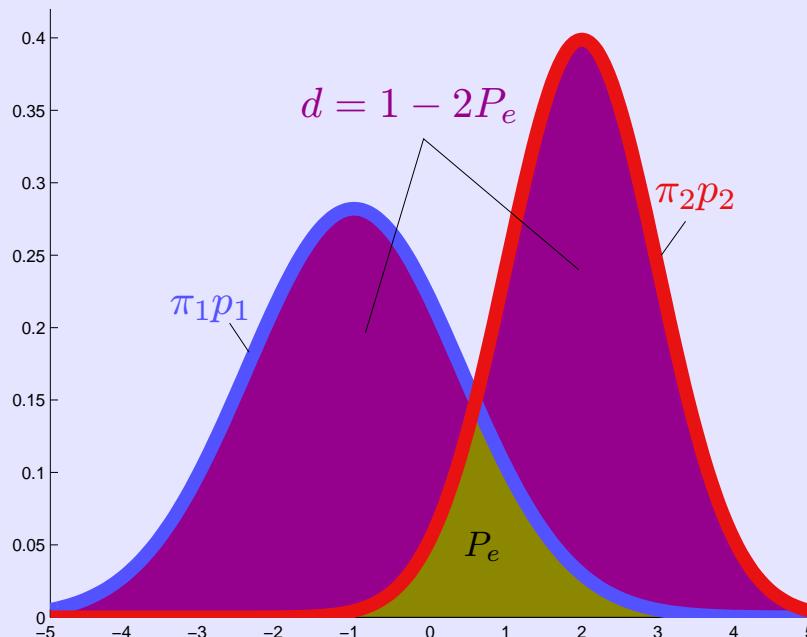


Bayes Error

Overlap of two pdfs p_1 and p_2 with prior probabilities π_1 and π_1 .

$$P_e(p_1(\mathbf{x}), p_2(\mathbf{x})) = \int_{\mathbf{x}} \min \{\pi_1 p_1(\mathbf{x}), \pi_2 p_2(\mathbf{x})\} d\mathbf{x}$$

$$d(p_1(\mathbf{x}), p_2(\mathbf{x})) = 1 - 2P_e(p_1(\mathbf{x}), p_2(\mathbf{x}))$$



SDTW/HMM Similarities

Alignment distance:

$$D_{\phi}(\mathcal{P}, \mathcal{R}) = \frac{1}{N} \sum_{i=1}^N d\left(\mathbf{P}_{\phi \mathcal{T}(i)}, \mathbf{R}_{\phi \mathcal{R}(i)}\right)$$

Viterbi distance:

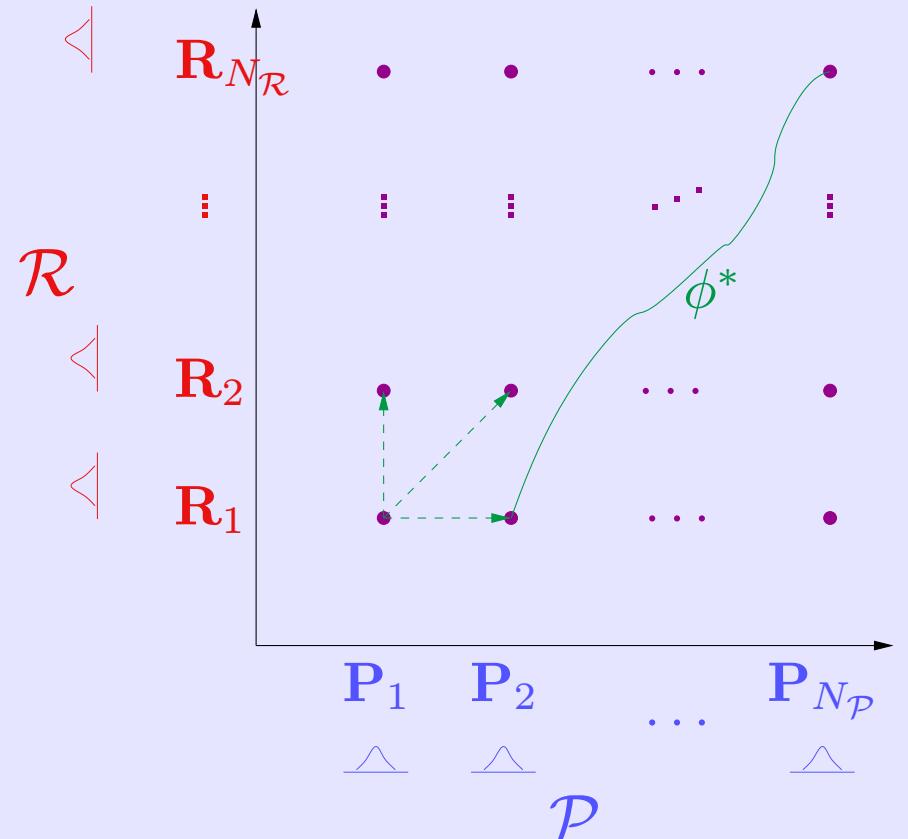
$$D(\mathcal{P}, \mathcal{R}) = D_{\phi^*}(\mathcal{P}, \mathcal{R}) = \min_{\phi} \{D_{\phi}(\mathcal{P}, \mathcal{R})\}$$

Local distance:

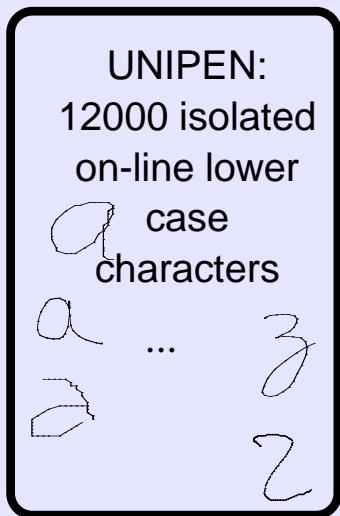
$$d(\mathbf{P}_i, \mathbf{R}_j) = 1 - 2P_e(\mathcal{N}(\mathbf{P}_i, \mathbf{x}), \mathcal{N}(\mathbf{R}_j, \mathbf{x}))$$

Backtransformation:

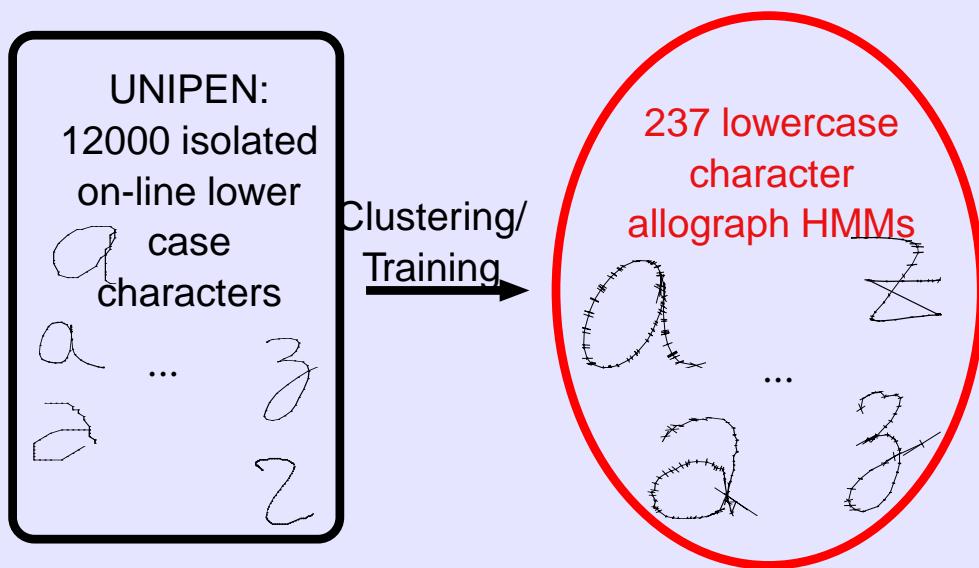
$$P_e^*(\mathcal{P}, \mathcal{R}) = \frac{1}{2}(1 - D(\mathcal{P}, \mathcal{R}))$$



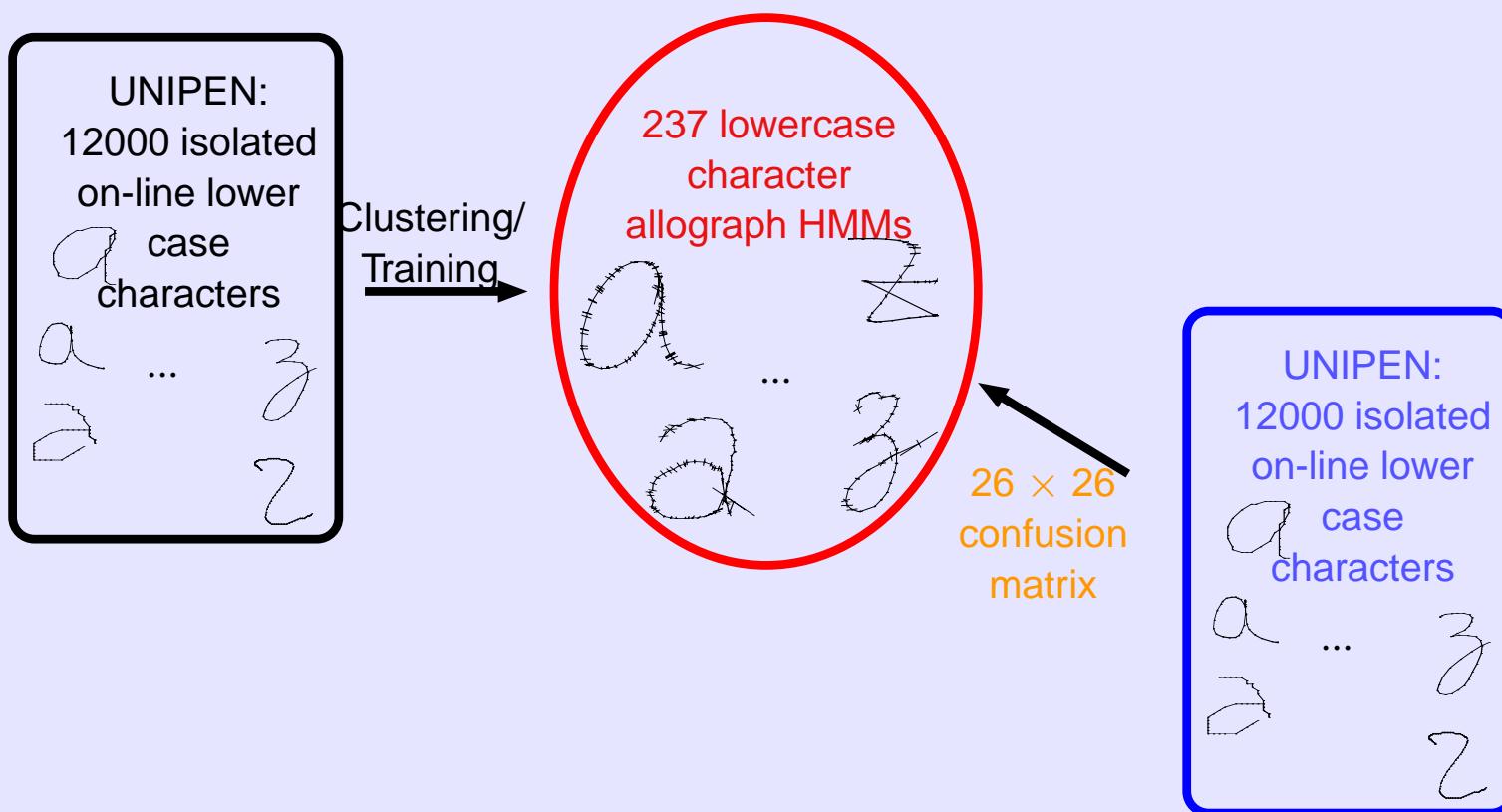
Description of experiments



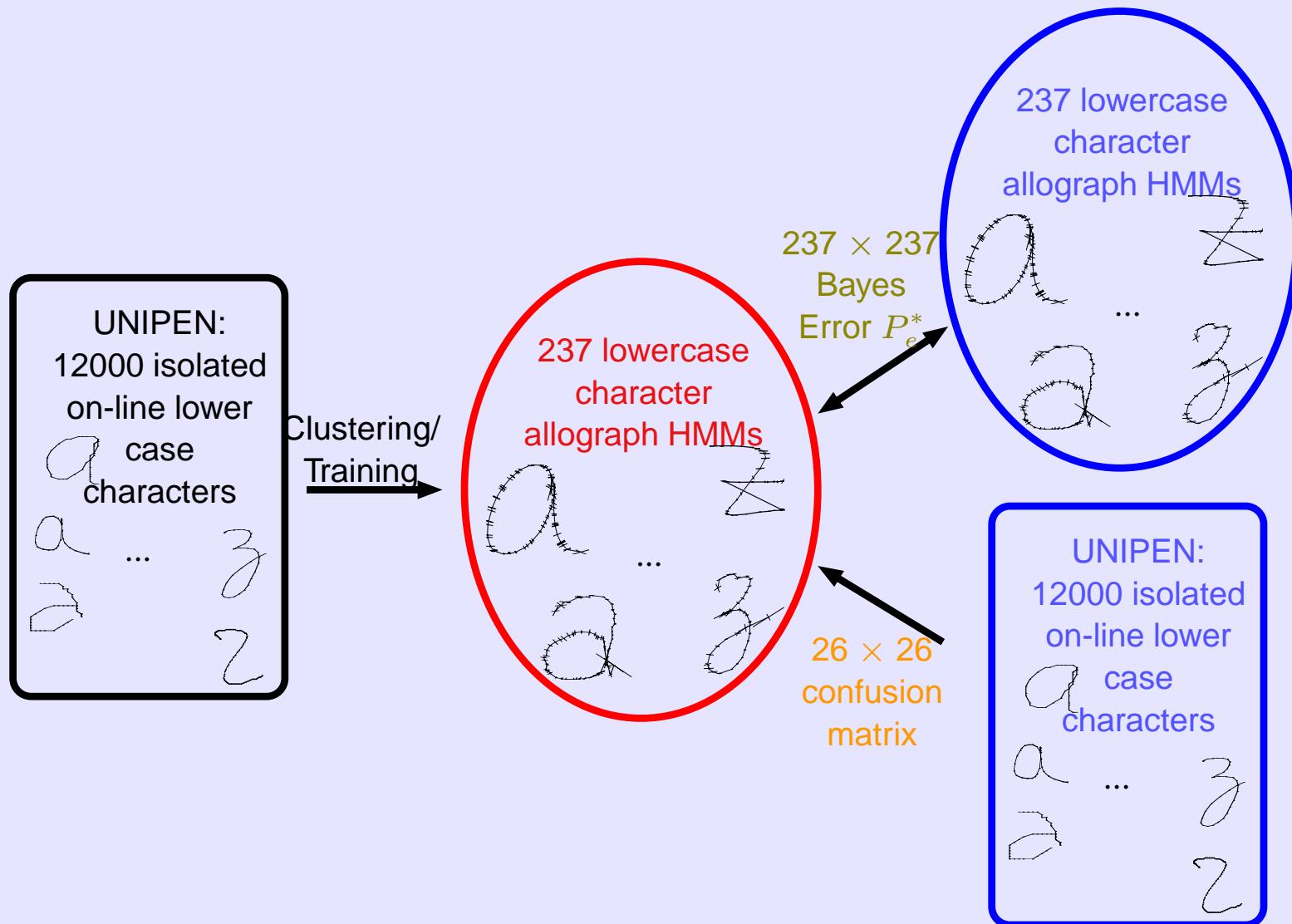
Description of experiments



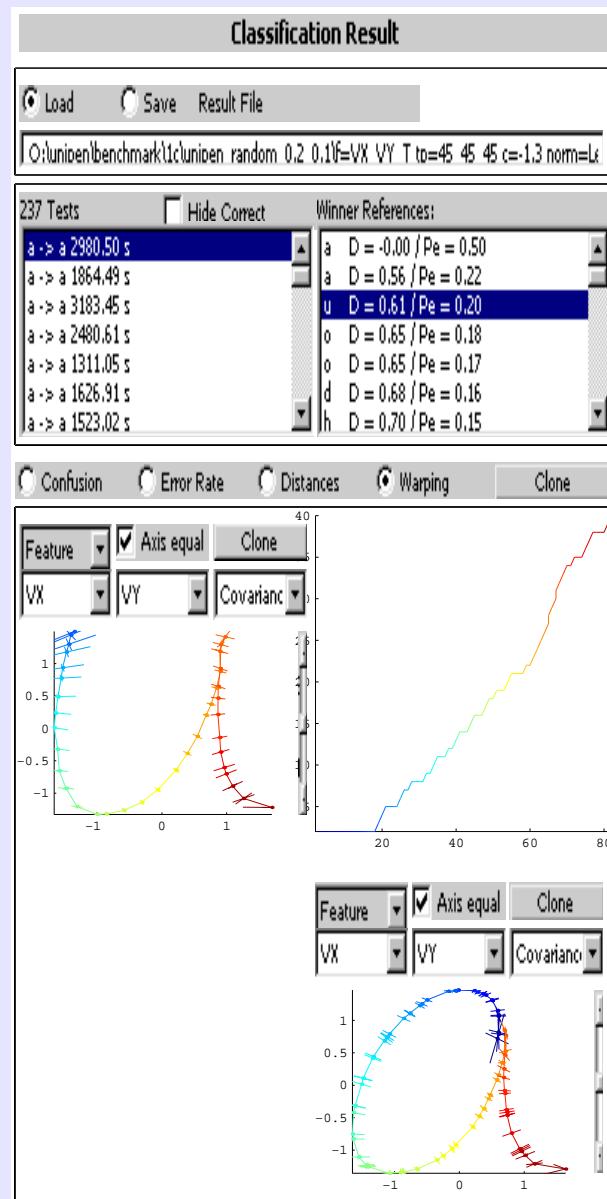
Description of experiments



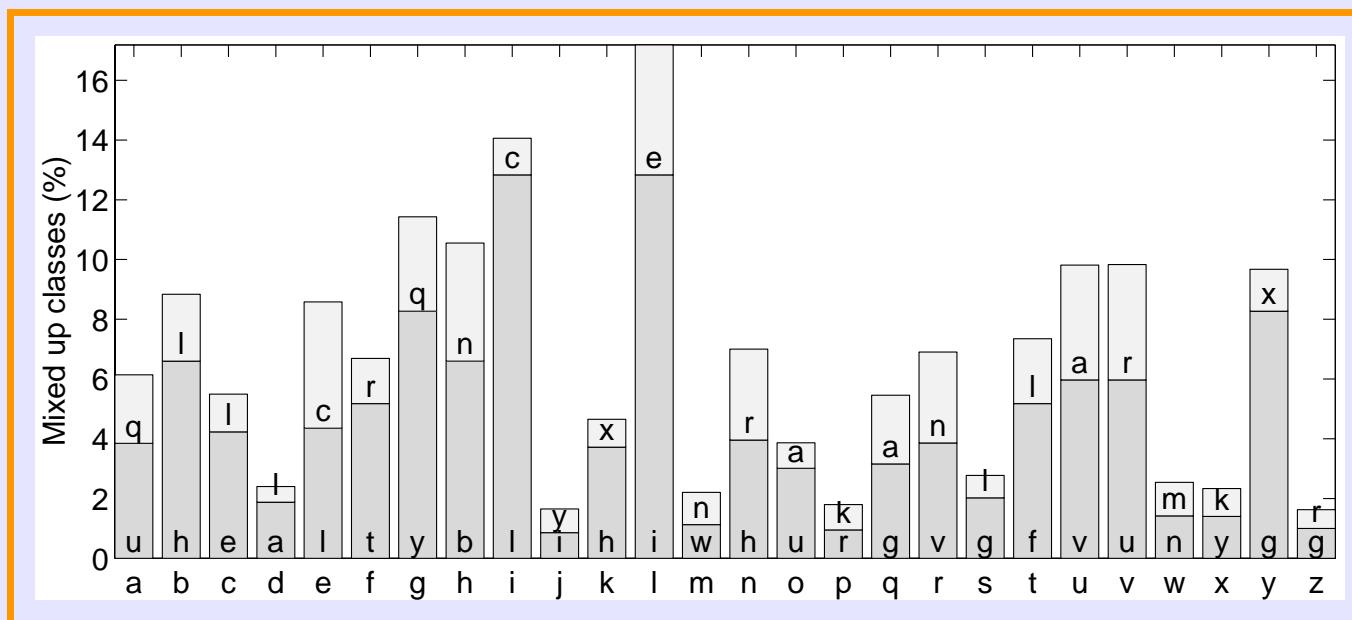
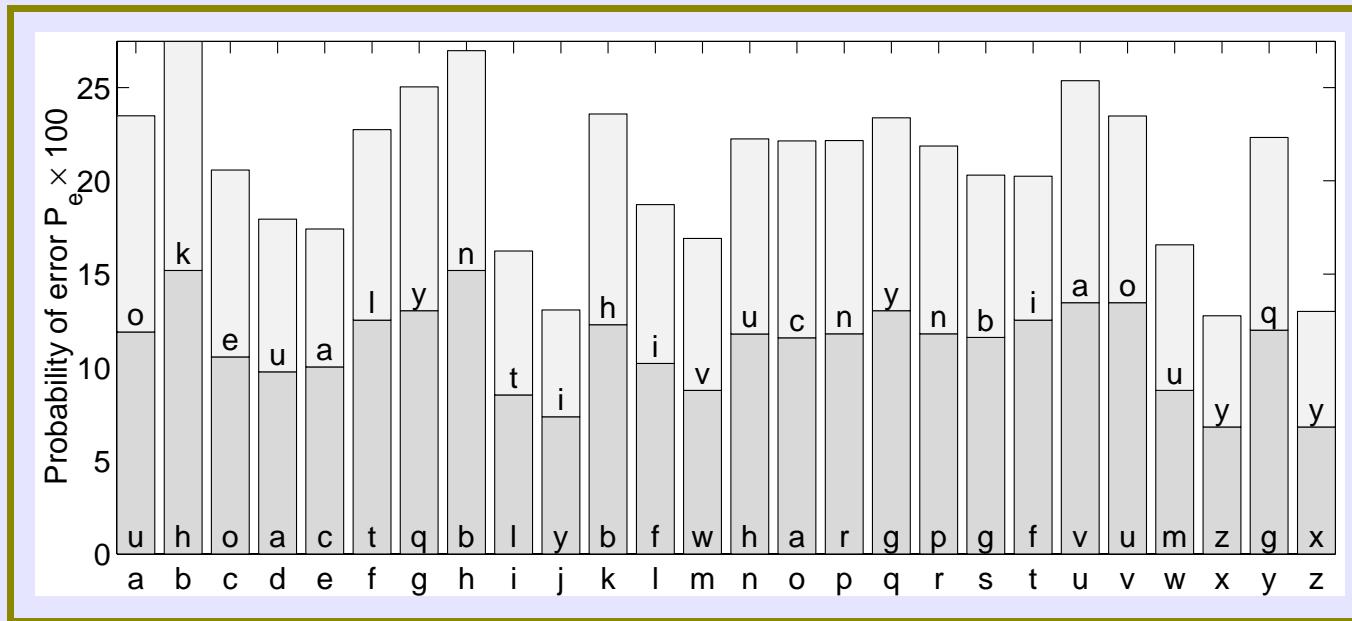
Description of experiments



Examples of Bayes error



Comparing Bayes Error and Classification Confusions



Conclusion

- Several Applications for distance measure
- Introduced HMM Similarity Measure
 - DTW / HMM classification as starting point
 - flexible in definition of local distance (Bayes error, χ^2 , Kullback-Leibler or Jensen-Shannon.)
 - not limited to handwriting recognition
- Experiments show
 - correspondence of similarity measure with visually assessed similarity
 - qualitative correlation of most similar and mostly confused classes

Future Work

- Discriminative training / hybrid classifiers for *similar* HMMs
- distance measure as stop criterion for iterative HMM training
- modeling transition probabilities
- Gaussian mixture models

Comparing Error Probability and Misclassifications

$P_e^* \left(\mathcal{R}^{l'k'}, \mathcal{R}^{lk} \right)$: Error probability of prototype $l'k'$ and lk

$C_{l',l}$: Number of classifications from class l into l'

Prob. of error	Misclassification
$237^2 \times P_e^* \left(\mathcal{R}^{l'k'}, \mathcal{R}^{lk} \right)$	$26^2 \times C_{l'l}$
↓	↓
$\tilde{P}_e^* (l', l) = \mathcal{E} \left[P_e^* \left(\mathcal{R}^{l'k'}, \mathcal{R}^{lk} \right) \right]_{k', k}$	$C'_{l'l} = C_{l'l} / (C_{l'l} + C_{ll})$
↓	↓
	$\tilde{C}_{l'l} = \tilde{\pi}_{l'l} C'_{l'l} + \tilde{\pi}_{l'l'} C'_{ll'}$

Feature Extraction

- Data:

polygon $[(x_i, y_i)]_{i=1, \dots, N_T}$

- Features:

- normalized x -coordinate $\tilde{x}_i = \frac{x_i - \mu_x}{\sigma_y}$
- normalized y -coordinate $\tilde{y}_i = \frac{y_i - \mu_y}{\sigma_y}$
- tangent angle $\theta_i = \text{ang}((x_{i+1} - x_{i-1}) + j \cdot (y_{i+1} - y_{i-1}))$

$$\text{feature vector } \mathbf{t}_i = (\tilde{x}_i, \tilde{y}_i, \theta_i)^T$$

$$\text{writing } \mathcal{T} = (\mathbf{t}_1, \dots, \mathbf{t}_{N_T})$$

